ORIGINAL PAPER



A hybrid deterministic and stochastic approach for tsunami hazard assessment in Iquique, Chile

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Received: 19 December 2018 / Accepted: 29 September 2019
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Abstract

The southern Peru and northern Chile coastal region is an active subduction zone that contains one of the most significant seismic gaps in the eastern Pacific basin (~17°S-~24°S). Although the gap was partially filled by the 2014 M_w 8.1 Iquique earthquake, there is still a high seismogenic potential to release a $M_w \sim 9$ earthquake in the near future; therefore, all the near-field coastal cities in the region face a latent tsunami threat. In this article, we propose a hybrid deterministic-stochastic multi-scenario approach to assess the current tsunami hazard level in the city of Iquique, an important commercial and industrial center of northern Chile that is home to 184,000 inhabitants. In our approach, we defined 400 stochastic, 10 deterministic and 10 homogeneous tsunamigenic earthquake scenarios, covering the entire area of the seismic gap. Based on the regional distribution of gravity anomalies and published interseismic coupling distributions, we interpreted the occurrence of four major asperities in the subduction interface of the seismic gap. The asperity pattern was used to construct a group of deterministic slip-deficit earthquake sources with seismic magnitudes ranging between M_w 8.4 and M_w 8.9. Additionally, we constructed 10 homogeneous slip scenarios to generate an inundation baseline for the tsunami hazard. Subsequently, following a stochastic scheme, we implemented a Karhunen-Loève expansion to generate 400 stochastic earthquake scenarios within the same magnitude range as the deterministic slip-deficit sources. All sources were used as earthquake scenarios to simulate the tsunami propagation and inundation by means of a non-hydrostatic model (Neowave 2D) with a classical nesting scheme for the city of Iquique. We obtained high-resolution data for flow depth, coastal surface currents and sea level elevation. The results suggest that the peak slip location and shelf resonance play an important role in the calculated coastal flow depths. The analysis of the entire set of simulated stochastic earthquake scenarios indicates that the worst-case scenario for Iquique is a M_w 8.9 earthquake. This scenario presented a tsunami arrival time of ~12 min, which is critical for the evacuation process. In addition, the maximum wave height and tsunami flow depth were found to be ~10 m and ~24 m, respectively. The observed coastal resonance processes exhibit at least three destructive tsunami wave trains. Based on historical and instrumental catalog statistics, the recurrence time of the credible worst-case earthquake scenario for Iquique (M_w 8.9) is 395 years, with a probability of occurrence of ~11.86% in the next 50 years.

Electronic supplementary material The online version of this article (https://doi.org/10.1007/s1106 9-019-03809-8) contains supplementary material, which is available to authorized users.

Published online: 08 October 2019

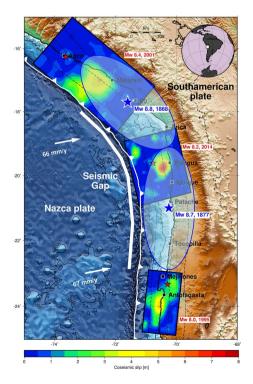


 $\textbf{Keywords} \ \ \text{Earthquake scenarios} \cdot \text{Tsunami hazard assessment} \cdot \text{Southern Peru} \cdot \text{Northern Chile}$

1 Introduction

The coastal region of southern Peru and northern Chile, extending between 17°S and 24°S, is located in the active subduction zone formed by the convergence of the Nazca and South American plates (Fig. 1). The segment has been recognized as one of the most significant seismic gaps in the eastern Pacific basin (Comte and Pardo 1991; Kelleher 1972; McCann et al. 1979; Nishenko 1985). It has undergone a prolonged seismic quiescence since the two last large historical earthquakes occurred in southern Peru (M_w 8.8, 1868) and northern Chile (M_w 8.7, 1877). Detailed descriptions of the 1868 event reported an extended tsunami impact along more than 4000 km of the coast between Trujillo, Peru, and Chiloe Island, Chile (Soloviev and Go 1975). In northern Chile, the tsunami severely impacted the city of Arica, where tsunami wave heights of ~18 m were reported (Soloviev and Go 1975). The tsunami caused by the 1877 earthquake destroyed many cities in northern Chile, including Arica, Iquique, Cobija and Mejillones. Historical reports mention tsunami waves heights of ~20 m in Mejillones harbor (Milne 1880; Soloviev and Go 1975; Vidal Gormaz 1878). More recently, the southern Peru and northern Chile seismic gap has been affected by moderate earthquakes, including the M_w 8.1 Antofagasta earthquake in 1995, the M_w 8.4 Arequipa earthquake in 2001, the M_w 7.7 Tocopilla earthquake in 2007 and the M_w 8.2 Iquique earthquake in 2014 (Delouis et al. 1997; Hayes et al. 2014; Peyrat et al.

Fig. 1 Tectonic framework of the southern Peru and northern Chile seismic gap. Blue ellipses indicate the historical tsunamigenic earthquakes of 1868, M_w 8.8 and 1877, M_w 8.7. The coseismic slip distributions of moderate earthquakes (M_w >8) are taken from Hayes (2017)





2010; Ruiz and Madariaga 2018; Schurr et al. 2014; Tavera et al. 2002). The 1995 Antofagasta, 2001 Arequipa and 2014 Iquique earthquakes generated moderate tsunamis (An and Liu 2014; Catalán et al. 2015; Guibourg et al. 1997; Okal et al. 2002).

Several authors have reported that the seismic gap of southern Peru and northern Chile has the potential to generate an earthquake of up to $M_{w} \sim 8.9$ in the near future (Hayes et al. 2014; Métois et al. 2013; Schurr et al. 2014; Seno 2014; Villegas-Lanza et al. 2016; Ye et al. 2018). Therefore, we can infer that a serious tsunami threat exists for all the coastal cities of southern Peru and northern Chile (Okal et al. 2006). Given this condition, this article proposes a methodology to estimate tsunami hazard using a multi-scenario approach. We consider multiple seismogenic sources, which can totally or partially fill the seismic gap. In order to define the earthquake scenarios, a hybrid deterministic-stochastic scheme was designed. In this approach, we assume that large tsunamis are generated by $M_w \ge 8.0$ earthquakes, whose locations and slip distributions on the causative fault are physically controlled by the frictional properties of the interplate contact, e.g., shear stress. The implicit idea of this assumption is that large earthquakes can represent the failure of a single asperity or a collection of two or more large asperities (Scholz and Campos 2012). We have defined a set of ~ 400 earthquake scenarios, which include stochastic variability of the slip distribution in a predefined framework of asperities. The earthquake scenarios are used as the initial condition assuming instantaneous deformation for tsunami simulation to estimate coastal impacts via parameters that include wave height, inland inundation area flow depth pattern, arrival time and spectral energy. The results obtained from the proposed methodology are used to estimate the state of tsunami hazard in the city of Iquique, the site of well-documented tsunami damage resulting from the 1868 and 1877 earthquakes.

2 Methodological approach

2.1 Earthquake scenarios

To provide deterministic tsunamigenic earthquake scenarios in the southern Peru and northern Chile seismic gap, we implemented a scheme for identifying the presence of major asperities, which can control the occurrence of future earthquakes. The locations of major asperities were inferred using a combination of trench-parallel gravity anomaly (TPGA), trench-parallel topography anomaly (TPTA) and available geodetic locking models. The spatial distribution of fault locking was used to estimate the slip deficit stored in the seismic gap since the 1868 M_w 8.8 earthquake in southern Peru and since the 1877 M_w 8.7 earthquake in northern Chile. The slip deficit was calculated using the convergence velocity model GEODVEL (Argus et al. 2010); it fluctuated between 65.3 and 67.3 mm/ year. This deterministic approach allowed tsunamigenic earthquake scenarios to be constructed. However, if we compare the dimensions of the maximum rupture area and the peak slip of the deterministic earthquake sources with realistic earthquakes extracted from a worldwide finite fault model database (Mai and Thingbaijam 2014), we obtain great differences (Fig. 2). In general, the deterministic earthquake sources have a lower peak slip than measured earthquakes; therefore, the deterministic approach can underestimate the tsunami parameters (Mueller et al. 2015). Thus, in a subsequent stage we calculated a large set of stochastic seismic scenarios with the slip distribution scaled to the moment magnitude.



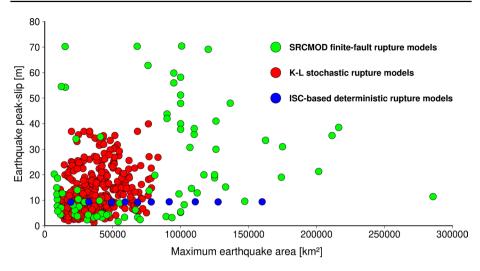


Fig. 2 Maximum earthquake area versus peak slip of worldwide finite fault rupture models extracted from SRCMOD database (Mai and Thingbaijam 2014) contrasted with interseismic coupling (ISC)-based and Karhunen–Lòeve (K–L) stochastic rupture patterns estimated by the multi-scenario tsunami hazard assessment approach

Large-amplitude negative TPGAs and TPTAs observed in the forearc region can be used as a proxy to evaluate the nucleation of earthquakes in the megathrust (Song and Simons 2003). These anomalies are usually used to infer the shear traction distribution in the interplate contact (Fletcher et al. 2001; Song and Simons 2003). A strong negative anomaly is related to relatively high shear tractions and vice versa. Under this paradigm, the shear traction controls the forearc topography, gravity patterns and, indirectly, the rupture areas of large earthquakes (Song and Simons 2003). The regional distribution of anomalies in the Nazca–South American subduction zone was calculated over 377 down-dip profiles projected on the fault contact geometry given by the Slab1.0 model (Hayes et al. 2012). The profiles extend from southern Peru (~14°S) to the Chile Triple Junction (~45°S). As an input to calculate the gravity and topography anomalies, we used the global marine free-air gravity of Sandwell et al. (2014) and the GEBCO world bathymetric model (The General Bathymetric Chart of the Oceans, Weatherall et al. 2015), respectively (Figures S1 and S2, Supplementary material).

The geodetic locking can be defined as the ratio between the slip rate on the megathrust fault during an interseismic period and the plate convergence velocity (Chlieh et al. 2011; Métois et al. 2016). We assume that areas governed by a high degree of locking correlate with the locations of asperities, whereas areas of reduced locking could represent barriers to earthquake propagation. To characterize these two elements, we used a published interplate locking model for the region extending from $\sim 17^{\circ}$ S in southern Peru to $\sim 24^{\circ}$ S in northern Chile (Métois et al. 2016).

Other authors have demonstrated that the spatial distribution of slip and the rupture complexity in a given earthquake constitute a first-order control on the hydrodynamic processes and coastal impacts of tsunamis (Geist 1998; Geist and Dmowska 1999; Mueller et al. 2015). For tsunami hazard assessment, the spatial distribution of the slip of historical or future megathrust earthquakes is complex (Mueller et al. 2015); thus, as standard practice numerical models utilize a preliminary homogeneous slip distribution estimated



from scaling laws (Allen and Hayes 2017; Blaser et al. 2010). To address this complexity, LeVeque et al. (2016) implemented a stochastic method using the Karhunen-Loève (K-L) expansion to generate static hypothetical rupture scenarios with non-uniform slip patterns. Subsequently, Melgar et al. (2016) extended this method to include kinematic rupture parameters and a 3D slab model. This new method was used to generate synthetic seismic waveforms to test the earthquake early warning (EEW) system in the Cascadia subduction zone (Melgar et al. 2016). We used this methodology to distribute the slip in the segmentation generated by the deterministic approach previously detailed in this section. The megathrust area of the southern Peru-northern Chile seismic gap was simulated using the geometry of the Slab 1.0 model (Hayes et al. 2012), which was discretized into 400 subfault elements. Following the findings of Li et al. (2016), each square subfault has size of 20 km per side to efficiently capture the rupture complexity of near-field region. We constructed the geometry of a particular scenario using a random subfault of the discretized space as a central locus to define an involved rupture area based on scaling laws proposed by Blaser et al. (2010). Subsequently, to define the statistics of the slip distribution, we assumed a normal slip distribution on each subfault, including a mean (μ_k) and standard deviation (σ_k) . Under this assumption, we defined a vector as containing a normally distributed slip that was characterized by a mean vector (μ) and a covariance matrix (\hat{C}) that was nominally defined as a fraction of the mean slip and an interfault correlation function (C_{ii}) , which controls the spatial statistics of slip (Melgar et al. 2016). The covariance matrix (\hat{C}) can be expressed in terms of eigenvalues (λ_k) and eigenvectors (v_k) (LeVeque et al. 2016); finally, the K–L expansion described the slip vector s as:

$$s = \mu + \sum_{k=1}^{N} z_k \sqrt{\lambda_k \nu_k} \tag{1}$$

where the z_k are normal random numbers with mean 0 and standard deviation 1.

As noted by Melgar et al. (2016), a potential weakness of this approach is the occurrence of negative values in calculated slip distributions of stochastic rupture scenarios. To solve this issue, LeVeque et al. (2016) propose an exponentiation of the slip vector s (Eq. 1) to produce a lognormal distribution, to assure a positive slip pattern. As example for our results, we plot the histograms of slip on each subfault from the 400 realizations, showing a reasonable fit with the theoretical marginal lognormal distribution (Figs. 3, S3, S4, S5 and S6). According to LeVeque et al. (2016), a large number of samples/scenarios (e.g., 20,000) are required to explore the statistical behavior of the K-L method. It is technically unfeasible to simulate this number of scenarios for high-resolution tsunami modeling. To define a minimum optimal number of stochastic scenarios, we used Welch's t test (Welch 1951). The t test checks if two populations have an equal mean. The slip distribution of the target population (20,000 scenarios) was compared with populations of 200, 300, 400, 1000, 2000, 5000 and 10,000 scenarios, indicating that a minimum of 400 scenarios is required to represent the statistical variability of the target population (Table 1). In addition, we performed a coefficient of variation analysis (Li et al. 2016), to support the selection of a minimum number of scenarios (Table 2).

The target magnitude was previously defined by the rupture area based on the deterministic approach. The target magnitudes range between M_w 8.3 and M_w 8.9 and are distributed among 0.06 magnitude bins. Following the methodology of Melgar et al. (2016), we constructed 40 scenarios per magnitude bin to complete 400 events and reach the minimum number of scenarios. To avoid unrealistically large amounts of slip that are sometimes



Fig. 3 Examples of histograms (blue) and marginal lognormal theoretical distribution with a μ =0 and σ =1 (red) of slip on selected subfault 050, 125, 251 and 347 (orange) from the 400 stochastic realizations. The fault geometry of earthquake scenario is denoted in green and limited by the magenta polygon

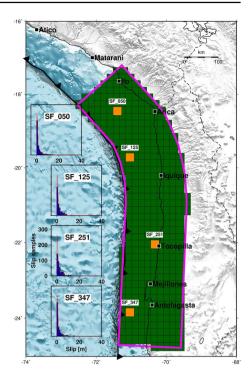


Table 1 Summary statistical parameters of *t* test analysis for stochastic scenarios

| Number of stochastic scenarios | Hypothesis test result ^a | p value |
|--------------------------------|-------------------------------------|---------|
| 200 | 1 | < 0.01 |
| 300 | 1 | < 0.01 |
| 400 | 0 | 0.54 |
| 1000 | 1 | < 0.01 |
| 2000 | 1 | < 0.01 |
| 5000 | 0 | 0.68 |
| 10,000 | 0 | 0.07 |
| 20,000 | 0 | 1 |

^a1, reject the null hypothesis that the data comes from normal distributions with equal means and equal unknown variances at the 5% of significance level; 0 otherwise

observed in stochastic scenarios, initially we use the deterministic approach to propose a baseline peak slip value based on the geodetic slip deficit of ~10 m since the 1877 M_w 8.7 event (Métois et al. 2016). Nevertheless, knowledge of the seismogenic behavior of the Chile–Peru seismic gap is restricted to a short time span of 500 years before the present (Comte and Pardo 1991; Lomnitz 2004), and it is unknown if the last large event in 1877 released all the slip deficits previously stored in the subduction zone. On the other hand, recent tsunamigenic earthquakes— M_w 9.2 Sumatra in 2004 (Chlieh et al. 2007; Piatanesi and Lorito 2007); M_w 8.8 Chile in 2010 (Lorito et al. 2011; Vigny et al. 2011); and M_w 9.0 Japan in 2011 (Pollitz et al. 2011; Simons et al. 2011)—have presented peak slip zones



Table 2 Summary statistical parameters of coefficient of variance (CoV) analysis for stochastic scenarios

| Number of stochastic scenarios | Coefficient of variation (CoV) |
|--------------------------------|--------------------------------|
| 200 | 1.44 |
| 300 | 1.45 |
| 400 | 1.48 |
| 1000 | 1.44 |
| 2000 | 1.43 |
| 5000 | 1.44 |
| 10,000 | 1.45 |
| 20,000 | 1.45 |

of 20 m, partially uncorrelated with high slip-deficit segments. Therefore, following the criteria used to balance the scenario variability and current tectonic knowledge of subduction zones presented by Melgar et al. (2016) and taking into account our deterministic slip-deficit baseline, we set the maximum peak slip in stochastic source simulations to 40 m.

2.2 Tsunami modeling

As mentioned earlier, the fault geometry in this work (e.g., slab depth, strike and dip) follows the Slab1.0 model (Hayes et al. 2012). For tsunami models, the rake angle of slip vector at the earthquake source is calculated using the mathematical relationship proposed by Michael (1990):

$$\lambda = \tan^{-1} \left[\frac{\tan \left(\theta \right)}{\cos \phi} \right] \tag{2}$$

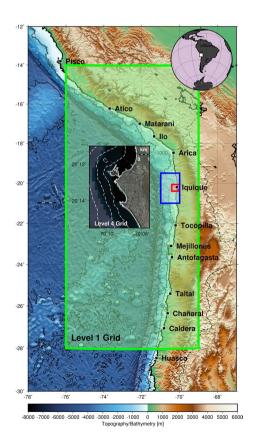
where θ is the convergence direction with respect to the fault strike and ϕ is dip of the fault. For the tsunami modeling, the down-dip limit of the seismogenic zone was constrained to a depth of ~70 km based on the available locking model (Métois et al. 2016). A down-dip boundary located between a depth of 40 and 50 km was proposed based on previous analysis of moderate earthquakes (Béjar-Pizarro et al. 2010; Sobiesiak et al. 2007) and thermal modeling (Oleskevich et al. 1999). In order to maintain a reasonable scale relationship among magnitude, rupture area and peak slip, we selected a deeper down-dip limit. The subduction fault was divided into subfault elements 20 km wide and long in agreement with the criteria proposed by Li et al. (2016) to improve the accuracy and decrease the dispersion effects of tsunami scenario modeling and achieve a reasonable computation time.

High-resolution tsunami numerical simulations were performed using the Non-hydrostatic Evolution of Ocean WAVEs model (NEOWAVE, Yamazaki et al. 2011). NEOWAVE is a two-dimensional, depth-integrated and non-hydrostatic model designed to describe dispersive waves and cope with flow discontinuities generated in hydraulic jumps, breaking waves and bores (Yamazaki et al. 2011). This model has recently been applied to analyze the generation, propagation and inundation processes of both far- and near-field tsunamis (Bai et al. 2014; Cheung et al. 2013; Lay et al. 2013; Yamazaki et al. 2013) and used for probabilistic design of coastal infrastructure (Cheung et al. 2011), shelf resonance analysis (Yamazaki and Cheung 2011) and post-tsunami surveys (Catalán et al. 2015; Aránguiz et al. 2016).



For precise calculation of inundation/runup processes, we set up four levels of nested grids for near-field tsunami scenarios. The level 1 grid, with a resolution of 2 arcmin (~3600 m), extended from central Peru (~14°S) to central Chile (~28°S), solving the seafloor deformation and near-field tsunami propagation along coastline. The level 2 grid, with a resolution of 30 arcsec (~900 m), and level 3 grid, with a resolution of 6 arcsec (~180 m), described the local scale of potential shelf and slope resonance of tsunami waves. The level 4 grid, with a resolution of 1 arcsec (~30 m), covered the coastal settlement of Iquique (~20°S). Results from this grid level were used to analyze the local variability of runup/inundation processes along the coastline. In addition, sea surface elevation, currents and spectral energy data from a synthetic tide gauge were analyzed. The level 1 and level 2 grids were extracted from the GEBCO world bathymetric model (Weatherall et al. 2015), the level 3 grids were constructed using regional nautical charts and SRTM (Shuttle Radar Topography Mission) data (Farr et al. 2007), and the level 4 grid was generated using local nautical charts combined with detailed bathymetry provided by the Ministry of Public Works and high-resolution LIDAR topography provided by the JICA-SATREPS project (Fig. 4). The topographic, bathymetric and coastline data were filtered, blended and gridded using computing algorithms of Generic Mapping Tools (GMT) (Smith and Wessel 1990; Wessel and Smith 2013). The simulations covered an elapsed time of 4 h, with computation time steps of 1, 0.5, 0.25 and 0.125 s for grids 1, 2, 3 and 4, respectively. The Manning's roughness coefficient was defined as 0.025, which is typical for ocean bottom.

Fig. 4 Nested grid setup and bathymetric data used for the modeling of near-field tsunami scenarios in the southern Peru and northern Chile seismic gap. The level 1 grid is highlighted by the green rectangle. The level 2 and 3 grids are shown in the blue and red rectangles, respectively. For the level 4 grid, we show the bathymetric contours (dashed lines) every 25 m of water depth gridded from local nautical charts





Spectral analysis of simulated tsunami waveforms was performed by a fast Fourier transform (FFT) algorithm (Frigo and Johnson 1998; Heidarzadeh and Satake 2014; Heidarzadeh et al. 2015). The FFT technique was applied for an elapsed time of 4 h in numerical simulation, with a modeling time window aimed at optimizing the computation time of all scenarios. The purpose of FFT is to characterize the spectral energy peaks associated with the seismic source and coastal resonance effects.

2.3 Probabilistic earthquake recurrence

The probabilistic earthquake recurrence assessment was developed to estimate the return period of the credible worst-case tsunamigenic scenario for the city of Iquique, located in the southern Peru and northern Chile seismic gap.

The estimation of earthquake recurrence time is not an easy task and is usually considered as one of the main sources of uncertainty in seismic and tsunami hazard assessment. We estimated the recurrence times of large megathrust earthquake scenarios using the Gutenberg–Richter relationship (Gutenberg and Richter 1944). First, we used a homogenized catalog in terms of moment magnitude based on an improved error-corrected method for the northern Chile zone (Das et al. 2018). The catalog includes historical and instrumental recorded events until 2016. A filtered subset of interplate seismicity was selected within the expected rupture polygon. The seismic parameters such as the *b*-value and earthquake recurrence rates were obtained from the Gutenberg–Richter relationship by means of the maximum likelihood methodology proposed by Weichert (1980). The Aki–Utsu estimator methodology from Kijko and Smit (2012) has been used to appraise the recurrence and the probabilities of occurrence of a range of magnitudes following the probability density function (Aki 1965):

$$f(m;\beta) = \beta e^{\left[-\beta(m - M_{\min})\right]} \quad \text{for} \quad m \ge M_{\min}$$
 (3)

The Gutenberg–Richter relationship normally considers the completeness above a given earthquake magnitude (M_{\min}) and an upper magnitude limit (M_{\max}). This upper limit was constrained by the expected maximum credible scenario magnitude (M_w 8.9), which is assumed to completely fill the seismic gap of southern Peru and northern Chile. However, due to the uncertainty of this maximum credible scenario, we prefer a more conservative approach, assuming a magnitude M_w 9.1 earthquake, as has been proposed in other studies (Ye et al. 2018).

3 Results

3.1 Deterministic earthquake scenarios

The analysis of two large-amplitude TPGAs and TPTAs suggests two segments with high shear traction in the seismic gap of southern Peru and northern Chile, which are interpreted as highly coupled zones (see Fig. 5a, b). One segment extends between Ilo and Pisagua (~18°S–~20°S); it is limited along-strike by the ruptures of the 2001 M_w 8.4 Arequipa earthquake (Ruegg et al. 2001) and the 2014 M_w 8.1 Iquique earthquake (Schurr et al. 2014). A second segment is located near the trench from Patache to the Mejillones Peninsula (~21°S–~23°S); it is limited along-strike by the 2014 M_w 8.1 Iquique earthquake and the 1995 M_w 8.0 Antofagasta earthquake (Delouis et al. 1997). Recent geodetic



Fig. 5 Geophysical parameters of southern Peru and northern Chile seismic gap. a Trench-parallel gravity ▶ anomaly, b trench-parallel topography anomaly, c interseismic coupling and d instrumental and historical seismicity catalog provided by Das et al. (2018)

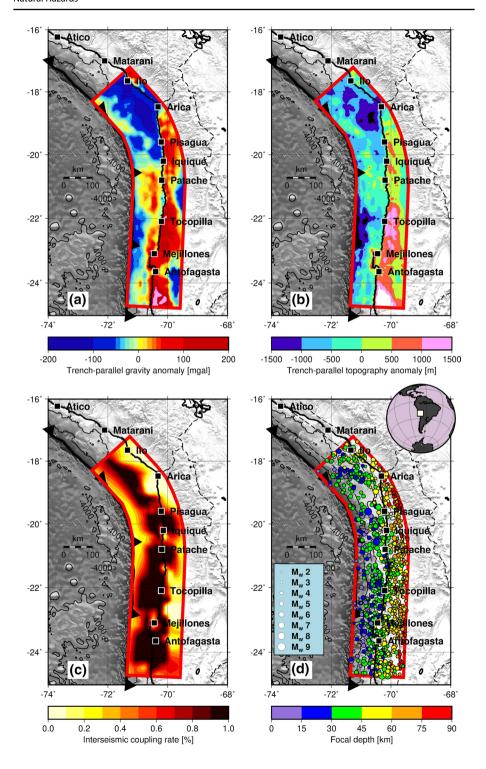
observations of the afterslip processes of the M_w 8.1 Iquique earthquake reinforced the idea of a seismotectonic barrier located at ~21°S (Hoffmann et al. 2018; Shrivastava et al. 2019). This segmentation can also be inferred based on available interseismic locking models (Chlieh et al. 2011; Métois et al. 2016) (see Fig. 5c). The instrumental and historical earthquake catalog provided by Das et al. (2018) shows a seismic quiescence in both segments, indicating a significant stress budget stored since the last major tsunamigenic earthquakes in 1868 and 1877 (see Fig. 5d). As a result, we obtained the geographical locations of four higher slip-deficit zones extending from ~18°S to ~24°S that can be interpreted as major remaining seismic asperities. Subsequently, the deterministic scenarios described in Sect. 2.1 were constructed by combining one or more asperities to generate ten plausible deterministic tsunami scenarios. The moment magnitudes range from M_w 8.4 to M_w 8.9 (Fig. 6 and Table S1).

3.2 Stochastic earthquake scenarios

Based on the geometry of the deterministic worst-case scenario (scenario 10, M_w 8.9, see Fig. 6), we generated 400 hypothetical earthquake rupture scenarios with a geologically constrained stochastic slip pattern supported by K–L expansion as outlined in LeVeque et al. (2016) and Melgar et al. (2016). In addition to the variable slip of non-uniform scenarios, we also observed variations around the mean length and width following the scaling law of Blaser et al. (2010), associated with estimated magnitudes. A brief overview of the distribution of sizes and magnitudes for the stochastic scenarios is presented in Fig. 7. In all these scenarios, we observed a reasonable fit with the selected scaling relationship. The rupture width of these scenarios did not present a saturation process, which is normally associated with the down-dip selection criterion, improving the moment magnitude calculation. Like Melgar et al. (2016), we observed a discrepancy between the target and actual moment magnitudes, which generated a more extended magnitude variation that ranges between M_w 8.0 and 9.1. Subsequently, we defined a stochastic worst-case tsunami scenario as the stochastic earthquake capable of generating the maximum flow depth at a specific coastal site in northern Chile.

Although our stochastic rupture scenario database consisted of a finite number of realizations (\sim 400), they are useful for progressing toward a comprehensive understanding of the relationship between physical processes of the rupture and the tsunami parameters. Previous works based on numerical and physical tsunami modeling (Plafker 1997; Rosenau et al. 2010; Ruiz et al. 2015) have shown a positive correlation between the maximum flow depth/runup and the increase in peak slip at the seismic source in a non-breaking wave regime. We observed a similar correlation pattern in some particular rupture scenarios; for example, two scenarios proposed for Iquique have an identical magnitude (M_w 8.88), but different peak slip locations and values, causing a disparity in flow depth estimation (Fig. 8; Table S2). Meanwhile, we expected a high tsunami runup at coastal sites using a specific source such as scenario 331 (M_w 8.86), which nucleated in a reduced along-strike section of the seismogenic zone (an effective length of \sim 350 km), but the constrained peak slip value was high (\sim 34 m). However, the regression relationship between peak slip and the maximum flow depth based on all







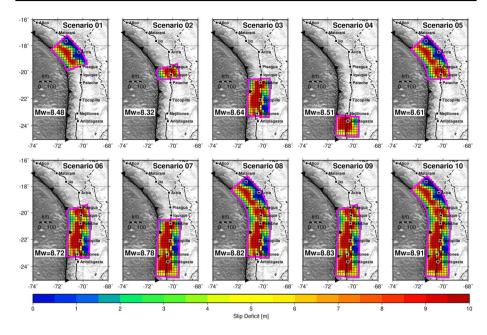


Fig. 6 Deterministic seismic scenarios based on geodetic slip deficit in southern Peru and northern Chile seismic gap

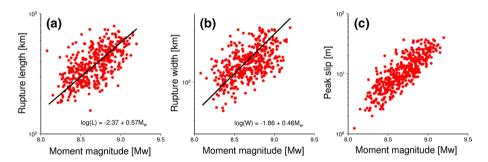


Fig. 7 Statistical parameters for K–L expansion stochastic scenarios, including a comparison with scaling laws proposed by Blaser et al. (2010). a Moment magnitude (M_w) versus maximum rupture length, b M_w versus maximum width length, c M_w versus peak slip

the stochastic models suggested a weak correlation (r=0.22), associated with the use of a wave breaking regime for the tsunami simulations. The same poor correlation was observed between the moment magnitude and the maximum flow depth (r=0.26) of the stochastic rupture scenarios (Fig. 9).

The maximum flow depth obtained from the deterministic tsunami scenarios was clearly underestimated in comparison with that obtained from stochastic sources (Fig. 9). The underestimation probably resulted from the low peak slip calculation caused by the smoothness included in the interseismic coupling models. The reported flow depths of historical tsunamigenic earthquakes in the seismic gap (Soloviev and Go 1975) fit reasonably well with the stochastic rupture scenarios, but we observed high



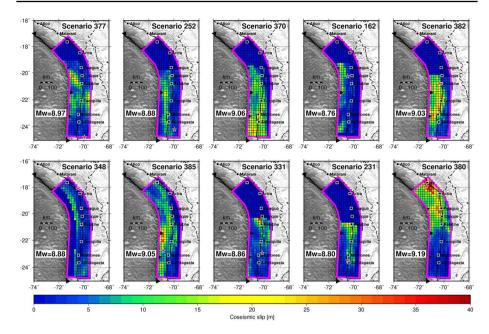


Fig. 8 Examples of megathrust earthquake scenarios based on the stochastic technique of K-L expansion

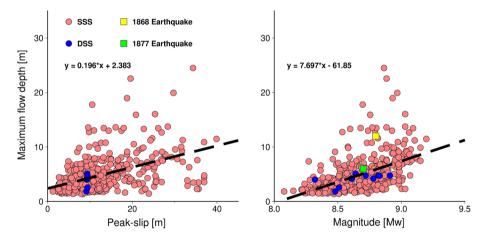


Fig. 9 Near-field modeled maximum flow depth versus peak slip and calculated moment magnitude (M_w) of stochastic seismic scenarios (SSS) and deterministic seismic scenarios (DSS) in the city of Iquique

variability in the results (Fig. 9). The peak slip magnitude can be a first-order control on the maximum flow depth on the coastline, but the high variability may be associated with other secondary factors such as edge waves, shelf resonance and other local effects related to coastal geomorphology (e.g., Catalán et al. 2015; Cheung et al. 2013; Melgar and Ruiz-Angulo 2018; Yamazaki et al. 2013).



3.3 Case study: tsunami modeling of credible worst-case scenario

To test the results of the stochastic scenarios, we carried out a detailed analysis of tsunami hazard in the city of Iquique (70°09′W; 20°13′S), which was selected as a case study due to the major damage caused by the earthquakes of 1868 and 1877, as well as the significant tsunami hazard exposure of its inhabitants (~184,000) and critical coastal infrastructure associated with its intense touristic, port and industrial activities (Aguirre et al. 2018).

We previously defined the credible worst-case scenario as a stochastic earthquake that produces a maximum flow depth at a specific site. In Iquique, the maximum flow depth of 24.51 m is associated with stochastic scenario 377 (M_w 8.9). In the middle of the seismic gap, the credible worst-case scenario simulated for Iquique presents an extensive inundation of developed areas, reaching a total area of 5.86 km². In the northern section of the city, we notice a maximum tsunami intrusion of ~1.30 km with a flow depth varying between ~8 and 12 m, affecting the local business district. The area encompassing the port facilities, historical downtown and tourist zone exhibits a maximum horizontal inundation of ~1.27 km with a flow depth ranging from 9.70 to 15.55 m. Between Cavancha Cove and Brava Beach, the maximum runup estimated for the simulation domain is ~19.89 m, with a maximum tsunami intrusion of ~1.12 km (Fig. 10).

Latitudinal distribution of flow depth for uniform slip scenarios fluctuates between 1.86 and 7.55 m, whereas the deterministic sources reduce the maximum observed flow depth to ~4.75 m. Meanwhile, the K–L stochastic scenarios are characterized by a wider flow depth range, between 0.07 and 24.51 m. For comparison, we included the reported maximum flow depths of the M_w 8.8 1868 (~12 m) and M_w 8.7 1877 (~6 m) tsunamigenic earthquakes (Soloviev and Go 1975). Although the historical data indicate a smaller event (~12 m), the proposed worst-case scenario was chosen for reasons of conservatism (Tinti et al. 2011).

The tsunami timeline starts ~ 12 min after the mainshock, when the first waves arrive (Tables S3 and S4) from the northeast, with an observed wave height of ~ 5.79 m recorded in the synthetic tide gauge IQUI_7 (Figure S13 and Table S3) and flow depth of ~ 14.15 m (Table S5) near the business district and harbor facilities. The peak surface coastal current velocity is ~ 10.92 m/s recorded in IQUI_2 station (Table S6) in a cross-shore sense, observed between Brava Beach and Cavancha Point. A second wave arrives ~ 26 min after the mainshock, reaching a significant peak wave height recorded in IQUI_3 station (~10.55 m) (Figures S8 to S13), flow depth inundation of ~ 18.09 m (Table S5) and current velocity of ~ 10.69 m/s, recorded in IQUI_3 station (Table S6), close to Cavancha Point. Finally, a third wave arrives ~ 36 min after the mainshock, when the highest tsunami flow depth (~24.51 m, Table S5) near Cavancha Cove and an extensive inundation area (~6 km²) covering almost the entire area under a topographic elevation of 30 m are observed. Additionally, two of the main observed spectral peaks (9.75 and 13.84 min) could be related to the energy impact of the first waves (Table S7).

For an extended analysis, we integrated all flow depth information generated by the stochastic scenarios for the city of Iquique to construct some sample statistics such as the mean, standard deviation, coefficient of variation and maximum. The spatial distribution of the flow depth mean fluctuates between 0 and 20 m and presents a maximum value east of Cavancha Cove (~ 20 m). The local business district, located near the southeast part of El Colorado beach, is affected by an extensive inundation intrusion of ~ 1.5 km, presenting a mean flow depth range of $\sim 3-10$ m. The section between the Serrano Peninsula and Morro Point presents a tsunami intrusion of 1 km with a mean flow depth that fluctuates



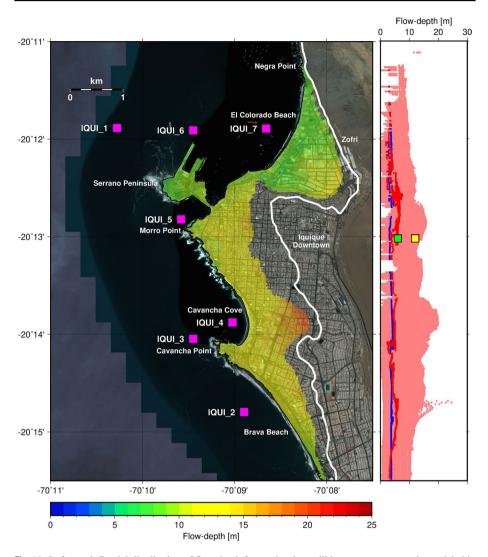


Fig. 10 Left panel: Spatial distribution of flow depth for stochastic credible worst-case scenario modeled in Iquique, including the reported flow depths of 1868 (yellow square) and 1877 (green square). The magenta square indicates the simulated sea level records stations. Right panel: Blue and red lines denote the deterministic maximum scenario (scenario 377, $M_w \sim 8.9$) and baseline homogeneous slip scenario, respectively. Pink lines show latitudinal distribution of flow depth for the 400 stochastic scenarios

from ~ 3 to 15 m. On the southern sandy beaches, we observed a mean flow depth between ~ 3 and 20 m and a maximum tsunami intrusion of 1 km (see Fig. 11a). The pattern of flow depth standard deviations presents a similar behavior, with a range of $\sim 0-2$ m. The lowest range of variation is an important value for the design of vertical evacuation infrastructure and tsunami evacuation routes. For example, we found that there is a specific site with a low range variation on the Serrano Peninsula, which is a potential location for vertical evacuation sites due to the possibility that the peninsula could become an island during a



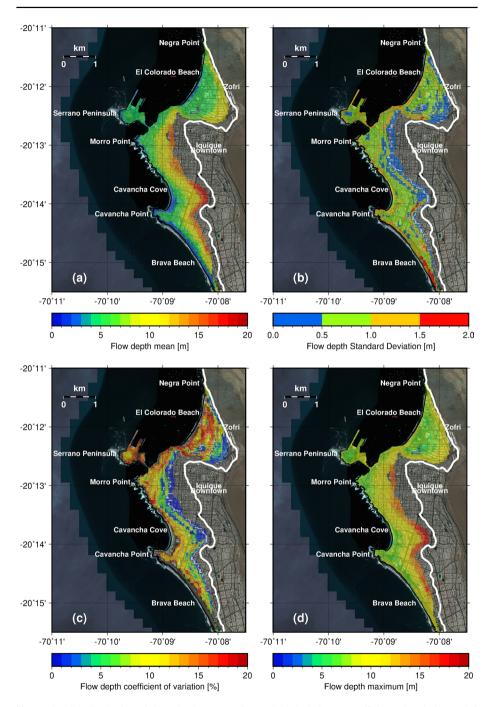


Fig. 11 Spatial distribution of flow depth a mean, b standard deviation, c coefficient of variation and d maximum estimated based on tsunami inundation of all stochastic scenarios modeled in Iquique



tsunami event (see Fig. 11b). The flow depth coefficient of variation is the ratio between the standard deviation and the mean and is useful for evaluating the homogeneity or low dispersion of the data; it can be represented by a percentage. A homogeneous system can be represented by a coefficient of variation under 2%. The level of the lowest dispersion of flow depth data can be found in the southeast section of the business district and in the easternmost area of the south central coastal segment (see Fig. 11c). The spatial distribution of the flow depth maximum fluctuates between ~4 and 20 m, with a maximum in the eastern section of the southern sandy beaches (see Fig. 11d).

Finally, based on the Aki–Utsu estimator methodology applied to the historical earth-quake catalog, we obtained the recurrence time in years and the probability of occurrence for a subset of magnitudes $(8.0 \ge M_w \ge 9.1)$ derived from the stochastic rupture scenario analysis. The estimated credible worst-case scenario in Iquique is a $M_w \sim 8.9$ event that produces a tsunami flow depth of 24.51 m, with a referential earthquake recurrence time of 395 years (Table S8).

4 Discussion

We used a semiquantitative approach to define a set of deterministic scenarios from relevant geophysical parameters, e.g., trench-parallel gravity anomalies, interseismic coupling distribution and historical and instrumental seismicity. The tsunamigenic sources calculated in this way exhibited a heterogeneous slip-deficit pattern, which is an improvement over the classical use of uniform slip sources for tsunami hazard assessment. Nevertheless, the use of slip-deficit deterministic sources in tsunami numerical models revealed a systematic underestimation of wave height, inundation area and flow depth, which ended up being comparable to those from uniform slip ruptures. While this slip-deficit approach has been used elsewhere, such as Watanabe et al. (2018), our results led us to question the validity or usefulness of slip-deficit sources to predict realistic impacts of future events. Thus, while our deterministic approach is an improvement, it clearly underestimates the coastal impacts of tsunamis based on records of historical earthquakes in the seismic gap (Milne 1880; Vidal Gormaz 1878). The failure of the slip-deficit sources can be attributed to the transient nature of interseismic coupling (Loveless and Meade 2016; Nishimura et al. 2004). Furthermore, whether large events release the entirety of the accumulated slip deficit or some deficit can persist between earthquake cycles is not known. All of these factors will invariably lead to an underestimation of the maximum peak slip of a seismic scenario (Métois et al. 2016).

Recently, the conventional asperity scheme provided by Lay and Kanamori (1981) has been improved using a categorization of global large megathrust earthquake rupture complexity (Ye et al. 2018). Based on the rupture complexity criterion, the southern Peru and northern Chile segment can be characterized by rough asperity patches, large interpatch separation, heterogeneous coupling and patch interaction prone to earthquake triggering. However, the modified asperity model proposed by Ye et al. (2018) can schematize the analyzed segment with only two main patches with M_w 8.6 for a single rupture and M_w 8.8 for a combined rupture, differing from our proposal of four asperity occurrences.

The aforementioned weakness of deterministic approaches can be overcome by employing a stochastic method to generate non-uniform slip distributions. In this work, the K–L expansion method (LeVeque et al. 2016; Melgar et al. 2016) leads to a wider variability of the maximum peak slip and distribution of the asperities in the scenarios. Furthermore, as also noted



by Li et al. (2016), this wide variability of seismic behaviors in modeled scenarios constitutes a powerful tool to evaluate the uncertainty of coastal tsunami data (Melgar et al. 2016). An important characteristic of the technique is the presence of extreme events in the scenario rupture catalog. For example, the scenario 380 (M_w 9.2) exhibits a single asperity that releases an extreme peak slip of ~39.89 m, concentrated along ~200 km of the rupture length. Meanwhile, the scenario 392 (M_w 8.9) presents a broad spatial length of ~542 km and a small value of slip released (~18.23 m). The specific characteristics of the selected scenarios illustrate the wide range of seismic behaviors in the rupture catalog, generating high variability and uncertainties in tsunami hazard assessment (Sepúlveda et al. 2017).

In order to improve the computation time needed to construct a robust scenario database, a finite number of tsunamigenic scenarios must be analyzed. According to statistical tests, we defined the minimum number of scenarios (400) needed to maintain the variability of our target population of 20,000 scenarios. For subsequent analysis, the stability of the variation coefficient applied to an exhaustive simulation database needs to be explored. The preliminary approach using the minimum number of scenarios is capable of providing a simplified view of the uncertainty in the hydrodynamic variables associated with the coastal impact of tsunamis.

The southern Peru and northern Chile seismic gap has been affected by two major tsunamigenic earthquakes in the last 150 years, which caused substantial damage in coastal cities such as Arica, Iquique, Tocopilla, Cobija and Mejillones. In the city of Iquique, the tsunami associated with the 1868 M_w 8.8 earthquake (Dorbath et al. 1990) generated a maximum tsunami inundation height of ~12 m and an extensive inundation area in the lower coastal zone near downtown (Soloviev and Go 1975). To validate the reported flow depth, values of this event can be compared with the stochastic scenario flow depth database. The spatial distribution of the flow depth mean ranged from ~4 to 12 m in the city's historical downtown, located approximately between Negra and Morro points. Other relevant reported information is the tsunami waves speed of 7 m/s (Soloviev and Go 1975), comparable to our results for the maximum scenario of ~10.92 m/s.

The empirical relationship observed between the maximum flow depth and peak slip presents a non-strong causative effect of a complex seismic source, opposed to findings reported by Geist (2002), mainly due to the flow depth calculation under breaking wave conditions. Most stochastic scenarios (~81%) present a peak slip that fluctuates between 1.24 and 20 m, with a high percentage (~95%) of flow depths less than 10 m. Extreme flow depth values over ~20 m can be associated with peak slips ranging between 20 and 40 m ($M_w \ge 8.5$). The scattering in the linear scaling could be related to the morphological effects of steep topographic gradients or harbor resonance processes.

The broad diversity of the stochastic seismic scenarios, presenting wide ranges of magnitudes and peak slip, can be useful for evaluating local effects using detailed inundation modeling, e.g., arrival time of tsunami waves for different scenarios (Figure S14). Furthermore, our comprehensive scenario database provides an initial multi-scenario tsunami hazard assessment, which, along with other considerations inherent to the risk analysis, can be useful for evaluating evacuation zoning, land-use planning and design of vertical evacuation structures.

5 Summary and conclusions

In this paper, we proposed a hybrid deterministic and stochastic approach to define the seismogenic potential of a mature seismic gap in southern Peru and northern Chile and subsequently perform a scenario-based tsunami hazard assessment of coastal



settlements. Initially, based on gravity models, instrumental seismicity and slip deficit derived from geodetic locking models, we defined a preliminary structure scheme of the main asperities and the maximum earthquakes associated with them. The tsunami simulation of these deterministic scenarios fails to match the historical flow depth reported in the city of Iquique, systematically underestimating it. To overcome this limitation, we adapted a novel stochastic technique based on the Karhunen-Loève (K-L) expansion to generate a database of rupture scenarios, including constrained fault geometry and reasonable restrictions on the maximum slip. Then, a data set of 400 stochastic scenarios was defined as the input for tsunami modeling performed using NEOWAVE. Finally, we obtained a database of tsunami wave heights, inundation extent, flow depth, arrival times and spectral energy. Here, we focused on the tsunami threat for the city of Iquique as a case study. The relationship between the maximum flow depth and peak slip shows that a complex source acts as a non-strong control on tsunami inundation, if we consider a wave breaking regime, with heterogeneous slip being a second-order control on the flow depth pattern during the inundation, compared to other factors affecting the hydrodynamic processes of inundation such as resonance and local morphology (Cortés et al. 2017; Ezersky et al. 2013). Opposite findings in Iquique have been reported by Sepúlveda et al. (2017), but considering a non-breaking wave regime.

The temporal evolution of the tsunami waves generated by the credible worst-case earthquake scenario in Iquique can be characterized by the impact of at least three main wave trains, with an initial arrival time of ~ 12 min after the mainshock. The maximum wave height, tsunami flow depth and horizontal intrusion occur the northern area of the city, close to business district and harbor facilities, and in the central section near Cavancha Cove, an important area for tourism. The maximum flow depth area is $\sim 6 \text{ km}^2$, covering nearly all the coastal areas below the safety line ($\sim 30 \text{ m}$ elevation). The calculated spectral peak of $\sim 13.84 \text{ min}$ has been reported by Cortés et al. (2017), indicating a reasonable simulation of coastal resonance processes.

The integration of complete flow depth information using sample statistics can be useful for determining evacuation protocols and the geographical locations of safe zones. For example, for the stochastic scenario database the maximum flow depth never exceeds the topographic level of 30 m, making this level suitable for demarcating the safe zone. Moreover, the combination of different sample statistics such as mean, standard deviation and coefficient of variation provides information for the design of evacuation routes and vertical evacuation buildings.

Acknowledgements This research has been funded by a Ph.D. scholarship awarded by Universidad Católica del Norte, Antofagasta, and the CONICYT FONDAP Program through Grant No. 1511017. We acknowledge the National Hydrographic and Oceanographic Service of the Chilean Navy for providing the local topography and bathymetric database used in the tsunami simulations. LIDAR high-resolution topography for Iquique was acquired through the JICA-JST SATREPS tsunami collaboration project, "Enhancement of Technology to Develop Tsunami-Resilient Community," between Chile and Japan. Global bathymetry data were extracted from GEBCO (http://www.gebco.net). Intensive tsunami modeling was supported by the supercomputing infrastructure of the National Laboratory for High Performance Computing (NLHPC/ECM-02) and the technical support of Mr. Diego Urrutia (Department of System and Computation Engineering, Universidad Católica del Norte, Antofagasta). We are thankful to Dr. Gonzalo Yáñez (Engineering School, Pontificia Universidad Católica de Chile, Santiago) for introducing the trench-parallel gravity anomaly (TPGA) methodology. Our acknowledgements to Dr. Roberto Benavente (Department of Civil Engineering, Universidad Católica de la Santísima Concepción) and Mr. Alejandro Urrutia (Research Center for Integrated Disaster Risk Management) for the valuable and fruitful comments. N. Zamora has been funded by the Fondecyt No. 3170895. Research funding for M.N. Shrivastava was provided by Fondecyt No. 3160773.



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